Spectrum Sensing in Cognitive Radios using Distributed Sequential Detection

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- Introduction
- Parametric Distributed Sequential Tests
- Nonparametric Distributed Sequential Tests
- Multihypothesis scenario
- Conclusions

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  - Sensing Frequency and duration

## Cooperative setup

- Mitigates multipath fading, shadowing and hidden node problem.
- ► Improves Probability of Errors (*P<sub>FA</sub>* and *P<sub>MD</sub>*) and Expected Detection Delay (*E<sub>DD</sub>*)
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 Distributed Detection: centralized



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## Problems addressed in this thesis (Contd.)

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- Channel gain statistic unknown (Universal Sequential Testing)
- Detect the spectrum and identify the primary user (Decentralized Multihypothesis Sequential Testing)

- Sequential tests: Wald'47, Irle'84
- Decentralized Sequential tests: Mei'08, Fellouris et al.'12, Yilmaz et al.'12
- Cooperative Spectrum Sensing and Censored detection: Akyildiz et al.'11
- Universal hypothesis tests: Levitan et al.'02, Jacob et al.'08, Unnikrishnan et al.'11
- Multihypothesis Sequential tests: Draglia et al.'99, Tartakovsky'00





General Problem: N = Stopping time,  $\delta_N =$  decision rule

 $\min_{N,\delta_N} E[N|H_0] \text{ and } \min_{N,\delta_N} E[N|H_1],$ 

subject to  $P_{F\!A} \leq \alpha_1$  and  $P_{MD} \leq \alpha_2$ 

#### **Parametric Distributed Sequential Tests**

► At / th CR,

$$H_0: X_{k,l} \sim f_{0,l}$$
  
 $H_1: X_{k,l} \sim f_{1,l}$ 

- $f_{0,I}$  and  $f_{1,I}$  are fully known
- $f_{0,l}$  and  $f_{1,l}$  are not fully known: parametric family.

1. At Node, I, Sequential Probability Ratio Test (SPRT),

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4. FC decides, at  $N = \inf\{k : F_k \notin (-\beta_0, \beta_1)\}$ ,  $H_1$  if  $F_N \ge \beta_1$ ,  $H_0$  if  $F_N \ge -\beta_0$ .









At each node I, time to cross the threshold

$$\mathcal{N}_I^1 \sim \mathcal{N}(rac{\gamma}{\delta_I}, rac{
ho_I^2 \gamma}{\delta_I^3}), \; \delta_I = \mathcal{E}_1[LLR_I] \; ext{and} \; 
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th order statistics of  $N_1^1, N_2^1, \ldots, N_L^1$ 

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$$I^* = min\{j : \delta^j_{FC} > 0 \text{ and } \frac{\beta - \overline{F}_j}{\delta^j_{FC}} < E[t_{j+1}] - E[t_j]\}$$

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►  $\bar{F}_j = E[F_{t_j-1}], \ \bar{F}_j = \bar{F}_{j-1} + \delta_{FC}^j (E[t_j] - E[t_{j-1}]), \ \bar{F}_0 = 0.$   
 $E_{DD} (E_1[N]) \approx E_1[N^1] \approx E[t_{I^*}] + \frac{\beta - \bar{F}_{I^*}}{\delta_{FC}^{I^*}}$ 

$$P_{MD} = P_1(N^0 < N^1) \ge P_1(N^0 < t_1, N^1 > t_1)$$

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# Performance Analysis of DualSPRT- P<sub>MD</sub>

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$$P_{MD} \approx \frac{P_1(N^0 < t_1)}{P_{k=1}} = \sum_{k=1}^{\infty} P\Big[ \{F_k < -\beta\} \cap_{n=1}^{k-1} \{F_n > -\theta\} | t_1 > k \Big] P[t_1 > k]$$

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P <sub>MD</sub> Sim.	P <sub>MD</sub> Anal.	E <sub>DD</sub> Sim.	E <sub>DD</sub> Anal.
18.78 <i>e</i> – 4	19.85 <i>e</i> – 4	44.319	43.290
26.68 <i>e</i> - 4	27.51 <i>e</i> – 4	36.028	34.634
36.30 <i>e</i> - 4	35.16 <i>e</i> – 4	27.770	25.977

 $\mathcal{R}_{c}(\delta) = \pi [c E_{0}(N) + W_{0}P_{0}\{reject H_{0}\}] + (1 - \pi)[c E_{1}(N) + W_{1}P_{1}\{rejectH_{1}\}]$ 

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- Sequential change detection formulation  $\mu_k = E[Y_k]$



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- What is the best test at FC?
- Sequential change detection formulation  $\mu_k = E[Y_k]$



• Reducing the false alarms caused by FC MAC noise before  $t_1$ .

$$F_{k}^{1} = \left(F_{k-1}^{1} + \log \frac{g_{\mu_{1}}(Y_{k})}{g_{z}(Y_{k})}\right)^{+}, F_{k}^{0} = \left(F_{k-1}^{0} + \log \frac{g_{z}(Y_{k})}{g_{-\mu_{0}}(Y_{k})}\right)^{-}$$

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- Sample path argument



### Modification of quantisation at SU's



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- First term dominates.

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## Comparison of Analysis with Simulations

- 5 Secondary nodes
- channel gains (0, -1.5, -2.5, -4 and -6 dB)
- $f_0 \sim \mathcal{N}(0, 1)$  and  $f_{1,l} \sim \mathcal{N}(\theta_l, 1), Var(Z_k) = 1$

P <sub>MD</sub> Sim.	P <sub>MD</sub> Anal.	E <sub>DD</sub> Sim.	E <sub>DD</sub> Anal.
0.00675	0.00613	26.8036	24.9853
0.0072	0.0065	33.1585	31.7624
0.01675	0.01624	30.0817	29.1322

#### Comparison with asymptotically optimal tests



Mei's SPRT: Mei, Trans. Inf. Theory 2008. DSPRT: Fellouris and Moustakides, Trans. Inf. Theory 2011.

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$$egin{array}{rcl} N&=&\inf\left\{n:W_{n,l}\geq g(cn)
ight\},\ g(t)&\approx&\log(1/t) ext{ as }t
ightarrow 0 \end{array}$$

▶ Decide upon  $H_0$  or  $H_1$  as  $\hat{\theta}_N \leq \theta^*$  or  $\hat{\theta}_N \geq \theta^*$  where  $\theta^*$  solves  $D(f_{\theta^*}||f_{\theta_0}) = D(f_{\theta^*}||f_{\theta_1})$ 

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- $D(f_{\theta}||f_{\lambda}) = E_{\theta}[\log[f_{\theta}(X)/f_{\lambda}(X)]$
- Similar to GLR test in Neyman-Pearson approach in FSS tests
- Diminishing uncertainty of θ̂<sub>n</sub> as an estimate of θ with n is incorporated into the varying stopping boundary g(cn)
- ▶ Asymptotically optimal over a broad range of  $\theta$  as  $c \rightarrow 0$

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hyp	E <sub>DD</sub>	$P_{E} = 0.1$	$P_{E} = 0.05$	$P_{E} = 0.01$
H1	DualSPRT	2.06	3.177	5.264
H1	GLRSPRT	1.425	2.522	4.857
H0	DualSPRT	1.921	3.074	5.184
H0	GLRSPRT	2.745	3.852	6.115

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## $H_0: f_{0,l} \sim \mathcal{N}(0, \sigma^2); H_1: f_{1,l} \sim \mathcal{N}(\theta, \sigma^2)$

where  $\theta$  is exponential distributed r.v which reflects the unknown channel gain.

## Simulation results

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Table: slow-fading between primary and secondary user under H0

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Table: slow-fading between primary and secondary user under H0

E <sub>DD</sub>	$P_{MD} = 0.1$	$P_{MD} = 0.08$	$P_{MD} = 0.06$
DualSPRT	1.74	1.854	2.417
GLRSPRT	1.62	3.065	5.42

Table: slow-fading between primary and secondary user under H1

## Comparison between SPRT-CSPRT and GLR-CSPRT

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Нур	E <sub>DD</sub>	$P_{E} = 0.1$	$P_{E} = 0.05$	$P_{E} = 0.01$
$H_1$	SPRT-CSPRT	1.615	2.480	4.28
$H_1$	GLR-CSPRT	1.138	2.221	4.533
$H_0$	SPRT-CSPRT	1.533	2.334	4.225
$H_0$	GLR-CSPRT	2.424	3.734	5.72

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▶ Rayleigh Slow fading:  $\sigma^2 = 1, \theta = exp(1), Var(Z_k) = 1$ 

Нур	E <sub>DD</sub>	$P_{E} = 0.1$	$P_{E} = 0.07$	$P_{E} = 0.04$
$H_1$	SPRT-CSPRT	1.03	1.53	2.347
$H_1$	GLR-CSPRT	0.94	1.004	4.225
$H_0$	SPRT-CSPRT	1.528	1.741	2.415
H <sub>0</sub>	GLR-CSPRT	2.615	3.192	4.237

#### **Universal Sequential Hypothesis Testing**

#### Universal sequential hypothesis testing problem Model for Single Cognitive Radio

- Nonparametric or universal setup:
  - Noise statistics under no PU transmission is fully known
  - Transmit power, channel gains, modulation schemes etc. of PU transmissions is not available (SNR uncertainty).
- i.i.d. observations  $X_i, i = 1, 2, \ldots$

$$H_0: X_i \sim P_0(\text{ p.d.f. } f_0) \text{ known }; H_1: X_i \sim P_1(\text{ p.d.f. } f_1) \text{ unknown}$$

$$N \stackrel{\Delta}{=} \inf\{n: W_n = \sum_{k=1}^n \log \frac{P_1(X_k)}{P_0(X_k)} \notin (-\gamma_0, \gamma_1)\},$$

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▶  $P_0$  is known;  $P_1$  is not known. Replace  $W_n$  by

$$\widehat{W}_n = -L_n(X_1^n) - \log P_0(X_1^n) - n\frac{\lambda}{2}, \, \lambda > 0.$$

 $L_n(X_1^n)$ =Codelength of a universal lossless source code for  $X_1^n$ 

By Shanon-Macmillan Thorem, for any stationary ergodic source lim<sub>n→∞</sub> n<sup>-1</sup> log P(X<sub>1</sub><sup>n</sup>) = -H
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Average drift under  $H_0$ :  $-\lambda/2$ Thus consider  $P_1$  belonging to the class

 $\mathcal{C} = \{P_1 : D(P_1, P_0) \geq \lambda\}.$ 

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(4)  $\frac{N}{|\log \gamma_0|} \xrightarrow{P_0 \text{ a.s.}}{\gamma_0, \gamma_1 \to \infty} \frac{2}{\lambda}; \ \frac{N}{|\log \gamma_1|} \xrightarrow{P_{1, \text{ a.s.}}}{\gamma_0, \gamma_1 \to \infty} \frac{1}{D(P_1||P_0) - \lambda/2}$ 

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(2)  $P_{FA} \stackrel{\Delta}{=} P_0(\widehat{W}_N \ge \gamma_1) \le \exp(-\gamma_1)$ .  
(3) Under (A),  $P_{MD} \stackrel{\Delta}{=} P_1(\widehat{W}_N \le -\gamma_0) = \mathcal{O}(\exp(-\gamma_0 s)), s > 0$ ..  
(4)  $\frac{N}{|\log \gamma_0|} \xrightarrow{P_0 \text{ a.s.}} \frac{2}{\lambda}; \frac{N}{|\log \gamma_1|} \xrightarrow{P_{1, a.s.}} \frac{1}{\mathcal{O}(\gamma_1 \to \infty)} \frac{1}{\mathcal{O}(P_1||P_0) - \lambda/2}$   
(5) Under (A), if  $E_1[(\log P_1(X_1))^{p+1}] < \infty \& E_1[(\log P_0(X_1))^{p+1}] < \infty$   
for some  $p \ge 1$ , then for all  $0 < q \le p$ ,  
 $\frac{E_0[N^q]}{|\log \gamma_0|^q} \xrightarrow{\gamma_0, \gamma_1 \to \infty} \left(\frac{2}{\lambda}\right)^q, \quad \frac{E_1[N^q]}{|\log \gamma_1|^q} \xrightarrow{\gamma_0, \gamma_1 \to \infty} \left(\frac{1}{\mathcal{O}(P_1||P_0) - \frac{\lambda}{2}}\right)^q$ 

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•  $X_k \to X_k^{\Delta} = [X_k/\Delta]\Delta;$ 

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$$\blacktriangleright H(X_1^{\Delta}) + \log \Delta \rightarrow h(X_1) \text{ as } \Delta \rightarrow$$

Test is modified to

$$\widetilde{W}_n = -L_n(X_{1:n}^{\Delta}) - n\log\Delta - \sum_{k=1}^n \log f_0(X_k) - n\frac{\lambda}{2}$$

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 $f_1 \in \mathcal{C} = \{f_1 : D(f_1, f_0) \geq \lambda\}.$ 

# Continuous alphabet case Why Uniform Quantization?

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- ► An adaptive uniform quantizer makes {X<sub>n</sub><sup>Δ</sup>} non i.i.d. L<sub>n</sub> unable to learn the underlying distribution in such scenario.
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• 
$$f_0(X_i)\Delta \approx p_0(X_i^{\Delta})$$
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- $f_0(X_i)\Delta \approx p_0(X_i^{\Delta})$ .  $\widetilde{W}_n = -L_n(X_i^{\Delta}) \sum_{j=1}^n \log p_0(X_i^{\Delta}) n\lambda/2$ .
- Range of the quantization: f<sub>1</sub>'s tail probabilities less than a small specific value at a fixed boundary

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 LZSLRT performance is close to the nearly optimal parametric GLR sequential tests and is better for some class of distributions (e.g. Pareto)

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 Universal codes defined via the K-T estimator and AE are nearly optimal

### Performance Comparison LZLRT

 $E_{DD} = 0.5 E_{H_1}[N] + 0.5 E_{H_0}[N]$  versus  $P_E = 0.5 P_{FA} + 0.5 P_{MD}$ 

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E <sub>DD</sub>	$P_{E} = 0.05$	$P_{E} = 0.01$	$P_{E} = 0.005$
SPRT	3.21	4.59	6.29
GLR-Lai	5.0	8.53	12.83
LZSLRT	12.95	15.19	19.29

Table:  $f_0 \sim \mathcal{N}(0,5)$  and  $f_0 \sim \mathcal{N}(3,5)$ 

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SPRT	7.45	10.86	18.23
GLR-Lai	18.21	29.65	33.42
LZSLRT	16.96	28.31	31.48

Table:  $f_0 \sim \mathcal{P}(10, 2)$  and  $f_0 \sim \mathcal{P}(3, 2)$ 

 $f_1 \sim \mathcal{N}(0,5)$  and  $f_0 \sim \mathcal{N}(0,1)$ , 8 bit uniform quantizer.



#### Performance Comparison Lognormal Distribution and Pareto Distribution examples

$$egin{aligned} & f_1 \sim \textit{In}\mathcal{N}(3,3) \text{ and} \ & f_0 \sim \textit{In}\mathcal{N}(0,3) \end{aligned}$$



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 $f_1 \sim \mathcal{P}(3,2)$  and  $f_0 \sim \mathcal{P}(10,2)$ , support set (2,10)



#### Performance Comparison Gaussian case ( $f_1 \sim \mathcal{N}(0, 5)$ and $f_0 \sim \mathcal{N}(0, 1)$ ) with different estimators

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1-NN differential entropy estimator is,  $\gamma =$  Euler-Mascheroni constant

$$\hat{h}_n = \frac{1}{n} \sum_{i=1}^n \log \rho(i) + \log(n-1) + \gamma + 1, \ \rho(i) \triangleq \min_{j:1 \le j \le n, j \ne i} ||X_i - X_j||$$

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Kernel density estimator at a point z is

$$\hat{f}_n(z) = rac{1}{w_n}\sum_{i=1}^n K\left(rac{z-X_i}{w_n}
ight)$$
, k: kernel and  $w_n$ : bandwidth

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Kernel density estimator at a point z is



#### Performance Comparison Comparison with Hoeffding Test: $P_0 \sim B(8, 0.2), P_1 \sim B(8, 0.5)$

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- noisy MAC between SUs and FC
- ▶ FC SPRT: binary hypothesis testing of  $g_{\mu_1}$  vs  $g_{-\mu_0}$

Performance Comparison

$$b_1 = 1$$
,  $b_0 = -1$ ,  $I = 2$ ,  $L = 5$  and  $Z_k \sim \mathcal{N}(0, 1)$ 

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 $f_{0,l} \sim \mathcal{N}(0,1)$  and  $f_{1,l} \sim \mathcal{N}(0,5)$ , for  $1 \leq l \leq L$ .

Performance Comparison

 $b_1 = 1, b_0 = -1, I = 2, L = 5 \text{ and } Z_k \sim \mathcal{N}(0, 1)$ 



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 $f_{0,l} \sim \mathcal{P}(10,2)$  and  $f_{1,l} \sim \mathcal{P}(3,2)$ , for  $1 \leq l \leq L$ .

Performance Comparison

 $b_1 = 1$ ,  $b_0 = -1$ , I = 2, L = 5 and  $Z_k \sim \mathcal{N}(0, 1)$ 



Analysis using Perturbed Random Walk theory  $\widehat{W}_n = S_n + \xi_n, \xi_n/n \to 0 \text{ a.s.}$ 

#### Multihypothesis Decentralized Sequential Testing (distributions completely known)

# Multihypothesis Decentralized Sequential Testing: Algorithm-1 (DMSLRT-1)

• M Hypothesis (M > 2),  $H_i : X_n \sim f^i$ ,  $i = 0, \ldots, M - 1$
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$$\begin{split} W_{n,l}^{k,j} &= W_{n-1,l}^{k,j} + \log \frac{f_l^k(X_{n,l})}{f_l^j(X_{n,l})}, W_{0,l}^{k,j} = 0\\ N_l &= \inf\{n : W_{n,l}^{k,j} > A \text{ for all } j \neq k \text{ and some } k\} \end{split}$$

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$$N_l = \inf\{n : W_{n,l}^{k,j} > A \text{ for all } j \neq k \text{ and some}$$
  
or  $N_l = \inf\{n : \max_{k} \min_{j \neq k} W_{n,l}^{k,j} > A\}$ 

k

• Use reflected random walks at local nodes,  $max(W_{n,l}, 0)$ 

- ► Use reflected random walks at local nodes, max(W<sub>n,l</sub>, 0) Decision by node l = H<sub>i</sub>
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- Instead of physical layer fusion, TDMA used.

► FC uses the same test with hypotheses  

$$G_m: Y_k \sim f_{FC}^m = \mathcal{N}(b_m, \sigma^2)$$

 $H_m: X_{k,l} \sim \mathcal{N}(m, 1), m=0, \dots, 4$ , No of local nodes=5



Figure: Comparison among different Multihypothesis schemes

 Reduce false alarms caused by Gaussian noise before first transmission from local nodes.

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- FC statistic is modified as

$$F_n^{i,j} = \widehat{F}_n^{i,0} - \widehat{F}_n^{j,0}, \text{ where } \widehat{F}_n^{i,0} = \max\left(\widehat{F}_{n-1}^{i,0} + \log \frac{f_{FC}^i(Y_n)}{f_Z(Y_n)}, 0\right).$$

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- Expected drift of  $\hat{F}_n^{i,0} > 0$  only when  $E[Y_n] > b_i/2$
- Positive  $b_i$ 's make  $E[F_n^{i,j}]$  negligible before first transmission

### Numerical results

SNRs (-10 dB, -6 dB, 0 dB and 6 dB), PU with SNR -10 dB uses the channel.



Figure: Comparison between MDSLRT-1 and MDSLRT-2

$$E_{DD}^{l} = E_{i}[N_{l}] \approx rac{A}{\min_{j \neq i} D(f_{l}^{i} || f_{l}^{j})}$$

E<sub>DD</sub> Analysis at SU: Dominant event-Reflected random walk with minimum positive expected drift

$$E_{DD}^{l} = E_{i}[N_{l}] \approx rac{A}{\min_{j \neq i} D(f_{l}^{i}||f_{l}^{j})}$$

Nonlinear renewal theory to take care of overshoots

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- Nonlinear renewal theory to take care of overshoots
- ▶ P<sub>FA</sub> Analysis at SU: Dominant event in {W<sup>k,j</sup><sub>n,l</sub>, k ≠ i}-when the expected drift is most negative.

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- Nonlinear renewal theory to take care of overshoots
- ▶ P<sub>FA</sub> Analysis at SU: Dominant event in {W<sup>k,j</sup><sub>n,l</sub>, k ≠ i}-when the expected drift is most negative.

► 
$$N_l^{k,j} = \inf\{n : W_{n,l}^{k,j} > A\}$$
;  $P_{FA}^l \approx P(\min_{k \neq i} N_l^{k,i} < N_l^{i\hat{j}})$   
 $\hat{j} = \operatorname{argmin}_{j \neq i} D(f_l^i || f_l^j)$ 

$$E_{DD}^{l} = E_{i}[N_{l}] \approx rac{A}{\min_{j \neq i} D(f_{l}^{i} || f_{l}^{j})}$$

- Nonlinear renewal theory to take care of overshoots
- ▶ P<sub>FA</sub> Analysis at SU: Dominant event in {W<sup>k,j</sup><sub>n,l</sub>, k ≠ i}-when the expected drift is most negative.
- ►  $N_l^{k,j} = \inf\{n : W_{n,l}^{k,j} > A\}$ ;  $P_{FA}^l \approx P(\min_{k \neq i} N_l^{k,i} < N_l^{i,\hat{j}})$  $\hat{j} = \operatorname{argmin}_{j \neq i} D(f_l^i || f_l^j)$
- $E_{DD}$  Analysis of DMSLRT-1:  $E_{DD} \approx E_i[\max_l N_l] + E_i[N_{FC}]$

Threshold $(A)$	E <sub>DD</sub> SimIn.	E <sub>DD</sub> Anal
100	157.54	141.61
120	186.98	169.34
140	216.31	197.07

Table: At SU: Comparison of  $E_{DD}$  obtained via simulation and analysis.

Threshold (A)	E <sub>DD</sub> SimIn.	E <sub>DD</sub> Anal	Threshold (A)	$P'_{FA}$ SimIn.	$P_{FA}^{l}$ Anal
100	157.54	141.61	8	0.0138	0.0296
120	186.98	169.34	10	0.0043	0.0093
140	216.31	197.07	20	5.00 <i>E</i> - 5	1.81E - 5

Table: At SU: Comparison of  $E_{DD}$  obtained via simulation and analysis.

Table: At SU: Comparison of  $P_{FA}$  obtained via simulation and analysis.

Threshold (A)	E <sub>DD</sub> SimIn.	E <sub>DD</sub> Anal	Threshold (A)	$P'_{FA}$ Simln.	$P_{FA}^{l}$ Anal
100	157.54	141.61	8	0.0138	0.0296
120	186.98	169.34	10	0.0043	0.0093
140	216.31	197.07	20	5.00 <i>E</i> - 5	1.81 <i>E</i> – 5

Table: At SU: Comparison of  $E_{DD}$  obtained via simulation and analysis.

Table: At SU: Comparison of  $P_{FA}$  obtained via simulation and analysis.

A	В	E <sub>DD</sub> SimIn.	E <sub>DD</sub> Anal
10	80	116.79	133.63
10	90	144.04	147.49
10	100	163.54	161.36

Table: DMSLRT-1: Comparison of  $E_{DD}$  obtained via simulation and analysis.

 Cooperating Spectrum Sensing algorithms in sequential detection framework

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- Universal sequential tests: discrete alphabet source (asymptotic properties derived), continuous alphabet source, decentralized scenario
- Decentralized multihypothesis Sequential tests: performance analysis, numerical comparisons

#### Thank You
### Publications based on this Thesis

- 1. J. K. Sreedharan and V. Sharma, "Spectrum sensing using distributed sequential detection via noisy MAC", submitted to journal.
- 2. J. K. Sreedharan and V. Sharma. "Nonparametric distributed sequential detection via universal source coding", in *Information Theory and Applications Workshop (ITA)*, California, USA, Feb 2013.
- J. K. Sreedharan and V. Sharma, "Spectrum Sensing via Universal Source Coding", in *Proc. IEEE Global Communications Conference* (GLOBECOM), California, USA, Dec 2012.
- 4. K. S. Jithin and V. Sharma, "Novel algorithms for distributed sequential hypothesis testing", in *Proc. 49th Annual Allerton Conference on Communication, Control and Computing*, Illinois, USA, Sep 2011 (invited paper).
- 5. J. K. Sreedharan and V. Sharma, "A novel algorithm for cooperative distributed sequential spectrum sensing in Cognitive Radio", in *Proc. IEEE Wireless Communications and Networking Conference (WCNC)*, Cancun, Mexico, Mar 2011.
- 6. K. S. Jithin, V. Sharma, and R. Gopalarathnam, "Cooperative distributed sequential spectrum sensing", in *Proc. IEEE National Conference on Communication (NCC)*, Bangalore, India, Jan 2011.

## Lemmas to support DualSPRT analysis

### Lemma 1

For i = 0, 1,  $P_i(N_i = N_i^i) \rightarrow 1$  as  $\gamma \rightarrow \infty$  and  $P_i(N = N^i) \rightarrow 1$  as  $\gamma \rightarrow \infty$  and  $\beta \rightarrow \infty$ .

#### Lemma 2

Under  $H_i$ , i = 0, 1 and  $j \neq i$ ,

(a) 
$$|N_l - N_l^j| \to 0$$
 a.s. as  $\gamma \to \infty$  and  $\lim_{\gamma \to \infty} \frac{N_l}{\gamma} = \lim_{\gamma \to \infty} \frac{N_l^j}{\gamma} = \frac{1}{D(f_{i,l}||f_{j,l})}$   
a.s. and in  $L^1$ .

(b) 
$$|N - N^i| \to 0$$
 a.s. and  $\lim \frac{N}{\beta} = \lim \frac{N'}{\beta}$  a.s. and in  $L^1$ , as  $\gamma \to \infty$  and  $\beta \to \infty$ .

#### Lemma 3

Let  $t_k$  be the time when k local nodes have made the decision. Under  $H_i$ , i = 0, 1, as  $\gamma \to \infty$ ,  $P_i$ (Decision at time  $t_k$  is  $H_i$  and  $t_k$  is the  $k^{th}$  order statistics of  $N_1^i, N_2^i, \ldots, N_L^i$ )  $\to 1$ .

## CR block diagram



Figure: Block diagram of the receiver implementation at a CR

 $P_{H_1}(FA before t_1)$ 

$$= \sum_{k=1}^{\infty} P\Big[\{F_{k} < -\theta\} \cap_{n=1}^{k-1} \{F_{n} > -\theta\} | t_{1} > k\Big] P[t_{1} > k]$$

$$= \sum_{k=1}^{\infty} \Big( P[F_{k} < -\theta| \cap_{n=1}^{k-1} \{F_{n} > -\theta\}] P[\cap_{n=1}^{k-1} \{F_{n} > -\theta\}] \Big)$$

$$P[t_{1} > k]$$

$$\stackrel{(A)}{=} \sum_{k=1}^{\infty} \Big( P[F_{k} < -\theta|F_{k-1} > -\theta] P[\inf_{1 \le n \le k-1} F_{n} > -\theta] \Big)$$

$$P[t_{1} > k]$$

$$\stackrel{(B)}{=} \sum_{k=1}^{\infty} \Big( \int_{c=0}^{2\theta} P[S_{k} < -c] f_{F_{k-1}} \{-\theta + c\} dc \Big)$$

$$\Big(1 - 2P[F_{k-1} < -\theta] \Big) \Big( \prod_{l=1}^{L} (1 - \Phi_{\tau_{\gamma,l}}(k)) \Big)$$

(A) is because of the Markov property of the random walk. (B) is due to the inequality,  $P[\sup_{k \le n} F_k \ge \theta] \le 2P[F_n \ge \theta]$  for the Gaussian R.W

# Gaussian Mean change approximation of Energy Detector

- ► X<sub>k,l</sub> are a summation of energy of N samples received by the l<sup>th</sup> Cognitive Radio
- For large *N*, the pre and post change distributions of  $X_{k,l}$  can be approximated by Gaussian distributions:  $f_{0,l} \sim \mathcal{N}(\sigma^2, 2\sigma^4/N)$  and  $f_{1,l} \sim \mathcal{N}(P_l + \sigma^2, 2(P_l + \sigma^2)^2/N)$  where  $P_l$  is the received power at the  $l^{th}$  CR node and noise  $Z_{k,l} \sim \mathcal{N}(0, \sigma^2)$ .
- Under low SNR conditions  $(P_l + \sigma^2)^2 \approx \sigma^4$  and hence  $X_{k,l}$  are Gaussian distributed with mean change under  $H_0$  and  $H_1$
- Take  $X_{k,l} \sigma^2$  as the data for  $l^{th}$  node SPRT.

- $X_{k,l}$  is the received power in decibels.
- ▶ pre change distribution of X<sub>k,l</sub> is N(μ<sub>0</sub>, σ<sub>l</sub><sup>2</sup>) and post change distribution N(μ<sub>0</sub> + P<sub>l</sub>, σ<sub>l</sub><sup>2</sup>)
- Secondary nodes are using Energy detector
- Under H<sub>0</sub> the uncertainty in noise and interference power is assumed to be log normally distributed. i.e log of the received power is Gaussian. μ<sub>0</sub> is mean noise power. σ<sub>1</sub><sup>2</sup> is the uncertainty in noise power.
- ▶ Under  $H_1$ ,  $P_l$  mean increase in received power due to the presence of primary.  $P_l = 10 \log_{10}(1 + SNR)$  dB.
- Log normal distribution is valid under H<sub>1</sub> as its used for modelling shadowing.

Under mild conditions the limiting distribution of the excess of a random walk over a fixed threshold does not change by the addition of a slowly changing nonlinear term.

$$E_{i}[N_{l}] \approx \frac{A + \mathcal{X}_{l}^{i\hat{j}} + \mathcal{B}_{l}^{i\hat{j}}}{D(f_{l}^{i}||\hat{f}_{l}^{j})},$$

where 
$$\mathcal{X}_{l}^{i\,\widehat{j}} = \frac{E_{i}[(R_{1,l}^{i,\widehat{j}})^{2}]}{2E_{i}[(R_{1,l}^{i,\widehat{j}})^{2}]} - \sum_{n=1}^{\infty} n^{-1}E_{i}S_{n,l}^{-i\,\widehat{j}}$$
 and  $\mathcal{B}_{l}^{i\,\widehat{j}} = -\sum_{n=1}^{\infty} n^{-1}E_{i}S_{n,l}^{-i\,\widehat{j}}$   
 $R_{k,l}^{i\,\widehat{j}} = \log(f_{l}^{i}(X_{k,l}/f_{l}^{\widehat{j}}(X_{k,l})) \text{ and } S_{n,l}^{-i\,\widehat{j}} = -\min(0, \sum_{k=1}^{n}R_{k,l}^{i\,\widehat{j}}).$ 

k=1